CSCE 313 Introduction to Computer Systems

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POSIX Threads

- Why Threads?
  - Latency Hiding / Multiprogramming (covered earlier)
  - Ease of Programming (covered now)
- POSIX Threads (R&R, Chapter 12)
  - Thread Management
  - Thread Safety
  - Thread Attributes
POSIX Threads

Why Threads?
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- Ease of Programming (covered now)

POSIX Threads (R&R, Chapter 12)
- Thread Management
- Thread Safety
- Thread Attributes

Why Threads?
- Many interactive applications run in loops.
- For example, an interactive game.

while (1) {
    /* Read Keyboard */
    /* Recompute Player Position */
    /* Update Display */
}

Reference [B.O. Gallmeister, "POSIX-4, Programming for the Real World," O'Reilly & Assoc., Inc.]
### Why Threads?

- Many interactive applications run in loops.
- For example, an interactive game.

```c
while (1) {
    /* Synchronize to Highest Frequency */
    /* Read Keyboard */
    /* AND Read Mouse */
    /* Recompute Player Position */
    /* Update Display */
    /* AND emit sounds */
}
```

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### Why Threads?

- It ain’t over yet!
- What about compute-intensive operations, like AI, video compression?
- How about Signal Handlers?

```c
while (1) {
    /* Synchronize to Highest Frequency */
    /* Read Keyboard */
    /* AND Read Mouse */
    /* Recompute Player Position */
    /* Update Display */
    /* AND all other lights */
    /* AND emit sounds */
    /* AND move game physically */
}
```

- Suddenly, application is getting complex!

- Reference [B.O. Gallmeister, "POSIX-4, Programming for the Real World," O'Reilly&Assoc., Inc.]
Reading the Mouse

while (1) {
    /* Synchronize to Highest Frequency */
    /* Read Keyboard */
    /* AND Read Mouse */
    /* Recompute Player Position */
    /* Update Display */
    /* AND all other lights */
    /* AND emit sounds */
    /* AND more sounds */
    /* AND move game physically */
}

read_mouse() {
}

Reading the Mouse (II)

while (1) {
    /* Synchronize to Highest Frequency */
    /* Read Keyboard */
    /* AND Read Mouse */
    /* Recompute Player Position */
    /* Update Display */
    /* AND all other lights */
    /* AND emit sounds */
    /* AND more sounds */
    /* AND move game physically */
}

int main() {
    read_mouse() {
        
    }
}

Separate Process

fork()
Reading the Mouse (III)

while (1) {
    /* Synchronize to Highest Frequency */
    /* Read Keyboard */
    /* AND Read Mouse */
    /* Recompute Player Position */
    /* Update Display */
    /* AND all other lights */
    /* AND emit sounds */
    /* AND more sounds */
    /* AND move game physically */
}

read_mouse() {
    return NULL;
}

Separate Thread

The Thread and its Creation

/* The Mouse Input Function */

void * read_mouse() {
    char buf[BUFSIZE]; ssize_t nbytes;
    for (;;) {
        if ((nbytes = read_from_mouse(buf, BUFSIZE)) <= 0)
            break;
        dosomething_with(buf, nbytes);
    }
    return NULL;
}
The Mouse Input Function

```c
void * read_mouse() {
    char buf[BUFSIZE];
    ssize_t nbytes;
    for (;;) {
        if ((nbytes = read_from_mouse(buf, BUFSIZE)) <= 0)
            break;
        dosomething_with(buf, nbytes);
    }
    return NULL;
}
```

The Thread and its Creation

```c
#include <pthread.h>
int error;
pthread_t tid;
if (error = pthread_create(&tid, NULL, read_mouse, NULL))
    perror("Failed to create read_mouse thread");

while (1) {
    /* Synchronize to Highest Frequency */
    /* Read Keyboard */
    /* AND Read Mouse */ <- Handled by separate thread!
    /* Recompute Player Position */
    /* Update Display */
    /* AND all other lights */
    /* AND emit sounds */
    /* AND more sounds */
    /* AND move game physically */
}
```

Thread Management

- `pthread_create` (create a thread)
- `pthread_self` (what is my id?)
- `pthread_equal` (two thread id’s equal?)
- `pthread_detach` (have thread release res’s)
- `pthread_join` (wait for a thread)
- `pthread_cancel` (terminate another thread)
- `pthread_exit` (exit a thread)
- `pthread_kill` (send a signal to a thread)

Most POSIX thread functions return 0 if successful and nonzero (error code) if unsuccessful
Thread Management

- `pthread_cancel` (terminate another thread)
- `pthread_create` (create a thread)
- `pthread_detach` (have thread release res’ s)
- `pthread_equal` (two thread id’s equal?)
- `pthread_exit` (exit a thread)
- `pthread_kill` (send a signal to a thread)
- `pthread_join` (wait for a thread)
- `pthread_self` (what is my id?)

```c
int pthread_create(pthread_t *restrict thread,
        const pthread_attr_t * restrict attr,
        void *(*start_routine)(void *),
        void *restrict arg)
```

```c
fd = open("my.dat", O_RDONLY);
if (error = pthread_create(&t_id, NULL, processfd, &fd))
    fprintf(stderr, "Failed create thread: %s\n", strerror(error));,
```

Thread Safety

- A function is thread-safe if multiple threads can execute simultaneous active invocations of the function without interference
  - Interference typically occurs when threads access the same (shared) data
- Some functions (not thread-safe) can have a thread-safe version designated with an _r suffix (e.g., `strerror` -> `strerror_r`)
Thread Attributes

| attribute objects | pthread_attr_destroy  
<table>
<thead>
<tr>
<th></th>
<th>pthread_attr_init</th>
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</table>
| state             | pthread_attr_getdetachstate  
|                   | pthread_attr_setdetachstate |
| stack             | pthread_attr_getguardsize  
|                   | pthread_attr_setguardsize  
|                   | pthread_attr_getstack      
|                   | pthread_attr_setstack     |
| scheduling        | pthread_attr_getinheritedsched  
|                   | pthread_attr_setinheritedsched  
|                   | pthread_attr_getschedparam  
|                   | pthread_attr_setschedparam  
|                   | pthread_attr_getschedpolicy  
|                   | pthread_attr_setschedpolicy  
|                   | pthread_attr_getscope      
|                   | pthread_attr_setscope      |

Thread Attributes: State

Detached threads release resources when terminate.

Attached states hold on to resources until parent thread calls pthread_join.
# Thread Attributes: Stack

<table>
<thead>
<tr>
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<tr>
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<td><code>pthread_attr_getstack</code></td>
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- **setstack** defines location and size of stack.
- **setguardsize** allocates additional memory. If the thread overflows into this extra memory, an error is generated.

# Thread Attributes: Scheduling

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<td>scheduling</td>
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- **PTHREAD_INHERIT_SCHED** defines that scheduling parameters are inherited from parent thread. (as opposed to **PTHREAD_EXPLICIT_SCHED**).
- Scheduling policies: SCHED_FIFO, SCHED RR, SCHED SPORADIC, SCHED OTHER, ...
- **contention scope** defines whether process competes at process level or at system level for resources.
```c
#include <pthread.h>
#include <stdio.h>
#include <string.h>
#define NUMTHREADS 10

static void *printarg(void *arg) {
    fprintf(stderr, "Thread received %d\n", *(int *)arg);
    return NULL;
}

int main (void) { /* program incorrectly passes parameters to threads */
    int error;
    int i;
    int j;
    pthread_t tid[NUMTHREADS];
    for (i = 0; i < NUMTHREADS; i++)
        if (error = pthread_create(tid + i, NULL, printarg, (void *)&i)) {
            fprintf(stderr, "Failed to create thread: %s\n", strerror(error));
            tid[i] = pthread_self();
        }
    for (j = 0; j < NUMTHREADS; j++) {
        if (pthread_equal(pthread_self(), tid[j]))
            continue;
        if (error = pthread_join(tid[j], NULL))
            fprintf(stderr, "Failed to join thread: %s\n", strerror(error));
    }
    printf("All threads done\n");
    return 0;
}
```